# Digital 16bit Serial Output Type Ambient Light Sensor IC 

BH1751FVI
No. 10046 EAT09

## -Descriptions

BH1751FVI is an digital Ambient Light Sensor IC for $I^{2}$ C bus interface. This IC is the most suitable to obtain the ambient light data for adjusting LCD and Keypad backlight power of Mobile phone. It is possible to detect wide range at High resolution.
( 1 - 65535 Ix ).

## -Features

1) I2C bus Interface ( $f / s$ Mode Support)
2) Spectral responsibility is approximately human eye response
3) Illuminance to Digital Converter
4) Wide range and High resolution. (1-65535 lx)
5) Low Current by power down function
6) $50 \mathrm{~Hz} / 60 \mathrm{~Hz}$ Light noise reject-function
7) 1.8 V Logic input interface
8) No need any external parts
9) Light source dependency is little. (ex. Incandescent Lamp. Fluorescent Lamp. Halogen Lamp. White LED. Sun Light )
10) It is possible to select 2 type of I2C slave-address.
11) Adjustable measurement result for influence of optical window (It is possible to detect min. 0.11 Ix, max. 100000 lx by using this function.)
12) Small measurement variation ( $+/-20 \%$ )
13) The influence of infrared is very small.
14) Build in power on reset circuit

## - Applications

Mobile phone, LCD TV, NOTE PC, Portable game machine, Digital camera, Digital video camera, Car navigation, PDA, LCD display

- Absolute Maximum Ratings

| Parameter | Symbol | Limits | Units |
| :--- | :---: | :---: | :---: |
| Supply Voltage | Vmax | 4.5 | V |
| Operating Temperature | Topr | $-40 \sim 85$ | ${ }^{\circ} \mathrm{C}$ |
| Storage Temperature | Tstg | $-40 \sim 100$ | ${ }^{\circ} \mathrm{C}$ |
| SDA Sink Current | Imax | 7 | mA |
| Power Dissipation | Pd | $260^{*}$ | mW |

$※ 70 \mathrm{~mm} \times 70 \mathrm{~mm} \times 1.6 \mathrm{~mm}$ glass epoxy board. Derating in done at $3.47 \mathrm{~mW} /{ }^{\circ} \mathrm{C}$ for operating above $\mathrm{Ta}=25^{\circ} \mathrm{C}$.

## -Operating Conditions

| Parameter | Symbol | Min. | Typ. | Max. | Units |
| :--- | :---: | :---: | :---: | :---: | :---: |
| VCC Voltage | Vcc | 2.4 | 3.0 | 3.6 | V |
| I$^{2}$ C Reference Voltage | VovI | 1.65 | - | Vcc | V |

- Electrical Characteristics (VCC $=\mathbf{3 . 0 V}, \mathrm{DVI}=3.0 \mathrm{~V}, \mathrm{Ta}=\mathbf{2 5}{ }^{\circ} \mathrm{C}$, unless otherwise noted )

| Parameter | Symbol | Min. | Typ. | Max. | Units | Conditions |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Supply Current | Icc1 | - | 120 | 190 | $\mu \mathrm{A}$ | $\mathrm{Ev}=100 \mathrm{~lx}{ }^{1}$ |
| Powerdown Current | Icc2 | - | 0.85 | 1.5 | $\mu \mathrm{A}$ | No input Light |
| Peak Wave Length | $\lambda p$ | - | 560 | - | nm |  |
| Measurement Accuracy | S/A | 0.96 | 1.2 | 1.44 | times | $\begin{aligned} & \text { Sensor out / Actual Ix } \\ & \text { EV }=1000 \mathrm{~lx} \approx^{1,} \varkappa^{2} \\ & \hline \end{aligned}$ |
| Dark ( 01 lx ) Sensor out | S0 | 0 | 0 | 3 | count | H-Resolution Mode *3 |
| H-Resolution Mode Resolution | rHR | - | 1 | - | Ix |  |
| L-Resolution Mode Resolution | rLR | - | 4 | - | Ix |  |
| H-Resolution Mode Measurement Time | thr | - | 120 | 180 | ms |  |
| L-Resolution Mode Measurement Time | tLR | - | 16 | 24 | ms |  |
| Incandescent / Fluorescent Sensor out ratio | rlF | - | 1 | - | times | $E V=1000 \mathrm{~lx}$ |
| ADDR Input 'H' Voltage | VAH | 0.7 * VCC | - | - | V |  |
| ADDR Input 'L' Voltage | VAL | - | - | 0.3 * VCC | V |  |
| DVI Input 'L' Voltage | VdVL | - | - | 0.4 | V |  |
| SCL, SDA Input 'H' Voltage 1 | VIH1 | 0.7 * DVI | - | - | V | DVI $\geqq 1.8 \mathrm{~V}$ |
| SCL, SDA Input 'H' Voltage 2 | VIH2 | 1.26 | - | - | V | $1.65 \mathrm{~V} \leqq \mathrm{DVI}<1.8 \mathrm{~V}$ |
| SCL, SDA Input 'L' Voltage 1 | VIL1 | - | - | 0.3 * DVI | V | DVI $\geqq 1.8 \mathrm{~V}$ |
| SCL, SDA Input 'L' Voltage 2 | VIL2 | - | - | DVI-1.26 | V | $1.65 \mathrm{~V} \leqq \mathrm{DVI}<1.8 \mathrm{~V}$ |
| SCL, SDA, ADDR Input 'H' Current | IIH | - | - | 10 | $\mu \mathrm{A}$ |  |
| SCL, SDA, ADDR Input 'L' Current | IIL | - | - | 10 | $\mu \mathrm{A}$ |  |
| $I^{2} \mathrm{C}$ SCL Clock Frequency | fscl | - | - | 400 | kHz |  |
| $I^{2} \mathrm{C}$ Bus Free Time | tBuF | 1.3 | - | - | $\mu \mathrm{s}$ |  |
| $I^{2} \mathrm{C}$ Hold Time ( repeated) START Condition | thDSTA | 0.6 | - | - | $\mu \mathrm{s}$ |  |
| $I^{2} \mathrm{C}$ Set up time for a Repeated START Condition | tsusta | 0.6 | - | - | $\mu \mathrm{s}$ |  |
| $I^{2} \mathrm{C}$ Set up time for a Repeated STOP Condition | tSUSTD | 0.6 | - | - | $\mu \mathrm{s}$ |  |
| $I^{2} \mathrm{C}$ Data Hold Time | tHDDAT | 0 | - | 0.9 | $\mu \mathrm{s}$ |  |
| $I^{2} \mathrm{C}$ Data Setup Time | tsudat | 100 | - | - | ns |  |
| $1^{2} \mathrm{C}$ 'L' Period of the SCL Clock | tLow | 1.3 | - | - | $\mu \mathrm{s}$ |  |
| $I^{2} \mathrm{C}$ 'H' Period of the SCL Clock | thigh | 0.6 | - | - | $\mu \mathrm{s}$ |  |
| $I^{2} \mathrm{C}$ SDA Output 'L' Voltage | Vol | 0 | - | 0.4 | V | $\mathrm{IOL}=3 \mathrm{~mA}$ |

[^0]
## -Reference Data



Fig. 1 Spectral Response


Fig. 4 Directional Characteristics 1


Fig. 7 Measurement Accuracy Temperature Dependency


Fig. 10 Vcc - Icc@0 Lx ( POWER DOWN )


Fig. 2 Illuminance Measuremnet Result 1


Fig. 5 Directional Characteristics 2


Fig. 8 Light Source Dependency (Fluorescent Light is set to ' 1 ')


Fig. 11 Measurement Result Vcc Dependency


Fig. 3 Illuminance Measuremnet Result 2


Fig. 6 Dark Response


Fig. 9 Vcc - Icc (During measurement)


Fig. 12 Measurement Result DVI Dependency

## -Block Diagram



## -Block Diagram Descriptions

- PD

Photo diode with approximately human eye response.

- AMP

Integration-OPAMP for converting from PD current to Voltage.

- ADC

AD converter for obtainment Digital 16bit data.

- Logic + ${ }^{2} \mathrm{C}$ Interface

Ambient Light Calculation and $I^{2} C$ BUS Interface. It is including below register.
Data Register $\rightarrow$ This is for registration of Ambient Light Data. Initial Value is "0000_0000_0000_0000".
Measurement Time Register $\rightarrow$ This is for registration of measurement time. Initial Value is "0100_0101".

- OSC

Internal Oscillator ( typ. 320kHz ). It is CLK for internal logic.

- POR

Power on reset. All register is reset after VCC is supplied. Please refer P. 8 (Caution of power on reset function).

## - Measurement Procedure



* "Power On" Command is possible to omit.


## OInstruction Set Architecture

| Instruction | Opecode | Comments |
| :---: | :---: | :---: |
| Power Down | 0000_0000 | No active state. |
| Power On | 0000_0001 | Waiting for measurement command. |
| Reset | 0000_0111 | Reset Data register value. Reset command is not acceptable in Power Down mode. |
| Continuously H-Resolution Mode | 0001_0000 | Start measurement at 11x resolution. Measurement Time is typically 120 ms . |
| Continuously H-Resolution Mode2 | 0001_0001 | Start measurement at 0.51 x resolution. Measurement Time is typically 120 ms . |
| Continuously L-Resolution Mode | 0001_0011 | Start measurement at $41 \times$ resolution. Measurement Time is typically 16 ms . |
| One Time H-Resolution Mode | 0010_0000 | Start measurement at 11x resolution. <br> Measurement Time is typically 120 ms . <br> It is automatically set to Power Down mode after measurement. |
| One Time H-Resolution Mode2 | 0010_0001 | Start measurement at 0.51 x resolution. Measurement Time is typically 120 ms . It is automatically set to Power Down mode after measurement. |
| One Time L-Resolution Mode | 0010_0011 | Start measurement at 4Ix resolution. <br> Measurement Time is typically 16 ms . <br> It is automatically set to Power Down mode after measurement. |
| Change Measurement time ( High bit ) | 01000_MT[7,6,5] | Change measurement time. <br> ※ Please refer "adjust measurement result for influence of optical window." |
| Change Masurement time (Low bit) | 011_MT[4,3,2,1,0] | Change measurement time. <br> ※ Please refer "adjust measurement result for influence of optical window." |

※ Don't input the other opecode.

## - Measurement mode explanation

| Measurement Mode | Measurement Time. | Resolurtion |
| :--- | :---: | :---: |
| H-resolution Mode2 | Typ. 120 ms. | 0.5 Ix |
| H-Resolution Mode | Typ. 120 ms. | 1 lx. |
| L-Resolution Mode | Typ. 16 ms. | 4 lx. |

We recommend to use H-Resolution Mode.
Measurement time (integration time ) of H-Resolution Mode is so long that some kind of noise( including in $50 \mathrm{~Hz} / 60 \mathrm{~Hz}$ noise ) is rejected. And H-Resolution Mode is 1 Ix resolution so that it is suitable for darkness (less than 10 lx ) H -resolution mode2 is also suitable to detect for darkness.

## - Explanation of Asynchronous reset and Reset command "0000 0111"

1) Asynchronous reset

All registers are reset and BH1751FVI becomes power down during DVI = 'L'. Initial reset is not necessary, because power on reset function is included in this product.
2) Reset command

Reset command is for only reset Illuminance data register. ( reset value is ' 0 ' ) It is not necessary after power supply to VCC because power on reset function is included in this product.
It is used for removing previous measurement result. This command is not working in power down mode, so that please set the power on mode before input this command.

## - Timing chart for VCC and DVI power supply sequence

DVI is $I^{2} \mathrm{C}$ bus reference voltage terminal. And it is also asynchronous reset terminal. In DVI ' L ' term, internal state is set to Power Down mode.Initial reset is not necessary, because power on reset function is included in this product. DVI supply with VCC supply, or after VCC supply. Please do not become DVI>VCC.

1) Recommended Timing chart1 for VCC and DVI supply.

2) Recommended Timing chart2 for VCC and DVI supply.
( If DVI can not supply with VCC supply )

VCC


## - Measurement sequence example from "Write instruction" to "Read measurement result"

ex1) Continuously H-resolution mode ( $\operatorname{ADDR}=$ ' L ' )

from Master to Slave

(1) Send "Continuously H-resolution mode " instruction

| ST | 0100011 | 0 | Ack | 00010000 | Ack | SP |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |

(2) Wait to complete 1st H -resolution mode measurement.( max. 180ms.)
(3) Read measurement result.

| ST | 0100011 | 1 | Ack | High Byte [15:8] | Ack |
| :--- | :--- | :--- | :--- | :--- | :--- |


| Low Byte [7:0] | $\overline{\text { Ack }}$ | SP |
| :--- | :--- | :--- |

How to calculate when the data High Byte is "10000011" and Low Byte is "10010000"

$$
\left(2^{15}+2^{9}+2^{8}+2^{7}+2^{4}\right) / 1.2 \fallingdotseq 28067[\mathrm{IX}]
$$

The result of continuously measurement mode is updated.( 120 ms .typ at H -resolution mode, 16 ms .typ at L-resolution mode )
ex2 ) One time L-resolution mode ( ADDR = 'H' )
(1) Send "One time L-resolution mode " instruction

| ST | 1011100 | 0 | Ack | 00100011 | Ack | SP |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |

(2) Wait to complete L-resolution mode measurement.( max. 24ms. )
(3) Read measurement result

| ST | 1011100 | 1 | Ack | High Byte [15:8] | Ack |
| :--- | :--- | :--- | :--- | :--- | :--- |


| Low Byte [7:0] | $\overline{\text { Ack }}$ | SP |
| :--- | :--- | :--- |

How to calculate when the data High Byte is "00000001" and Low Byte is "00010000"

$$
\left(2^{8}+2^{4}\right) / 1.2 \fallingdotseq 227[\mid x]
$$

In one time measurement, Statement moves to power down mode after measurement completion. If updated result is need then please resend measurement instruction.

## - Application circuit example



* $I^{2} C$ BUS is trademark of Phillips Semiconductors. Please refer formality specification for pull up resister.


## Caution of power on reset function

BH1751FVI has power on reset (POR) function. POR is to reset all register and flip flop when VCC Power supplies.
There are some cautions about power on and down sequence seeing in below.
(1) Power on time: t1

More than 2 ms is need to active BH 1751 FVI after VCC supplies more than 2.0 V from VCC is less than 0.4 V .
(2) Power off time: t2

More than $1 \mathrm{~ms}(\mathrm{VCC}<0.4 \mathrm{~V})$ is need to active BH1751FVI.


[^1]
## - $1^{2} \mathrm{C}$ Bus Access

1) $I^{2} C$ Bus Interface Timing chart

Write measurement command and Read measurement result are done by $\mathrm{I}^{2} \mathrm{C}$ Bus interface. Please refer the formally specification of $I^{2} C$ Bus interface, and follow the formally timing chart.

2)Slave Address

Slave Address is 2 types, it is determined by ADDR Terminal

$$
\text { ADDR = 'H' (ADDR } \geqq 0.7 \mathrm{VCC}) \rightarrow \text { " } 1011100 \text { " }
$$

$$
\text { ADDR = 'L' (ADDR } \leqq 0.3 \mathrm{VCC}) \rightarrow \text { "0100011" }
$$

3) Write Format

BH 1751 FVI is not able to accept plural command without stop condition. Please insert SP every 1 Opecode.

| ST | Slave Address | R/W <br> 0 | Ack | Opecode | Ack | SP |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |

4 ) Read Format


| $2^{7}$ | $2^{6}$ | $2^{5}$ | $2^{4}$ | $2^{3}$ | $2^{2}$ | $2^{1}$ | $2^{0}$ |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |


from Master to Slave

from Slave to Master
ex )
High Byte = "1000_0011"
Low Byte $=$ "1001_0000"
$\left(2^{15}+2^{9}+2^{8}+2^{7}+2^{4}\right) / 1.2 \fallingdotseq 28067[1 \mathrm{x}]$
${ }^{*} I^{2} C$ BUS is trademark of Phillips Semiconductors. Please refer formality specification.

## - Adjust measurement result for influence of optical window. (sensor sensitivity adjusting )

BH1751FVI is possible to change sensor sensitivity. And it is possible to cancel the optical window influence (difference with / without optical window) by using this function. Adjust is done by changing measurement time. For example, when transmission rate of optical window is $50 \%$ (measurement result becomes 0.5 times if optical window is set ), influence of optical window is ignored by changing sensor sensitivity from default to 2 times

Sensor sensitivity is shift by changing the value of MTreg (measurement time regisiter). MTreg value has to set 2 times if target of sensor sensitivity is 2 times. Measurement time is also set 2 times when MTreg value is changed from default to 2 times.
ex) Procedure for changing target sensor sensitivity to 2 times.
Please change Mtreg from"0100_0101" (default) to"1000_1010" (default * 2 ).

1) Changing High bit of MTreg

| ST | Slave Address | R/W <br> 0 | Ack | 01000_100 | Ack | SP |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |

2) Changing Low bit of MTreg

| ST | Slave Address | R/W <br> 0 | Ack | $011 \_01010$ | Ack | SP |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |

3) Input Measurement Command

4) After about 240 ms , measurement result is registered to Data Register.
( High Resolution mode is typically 120 ms , but measurement time is set twice. )
The below table is seeing the changable range of MTreg.

|  |  | Min. | Typ. | Max. |
| :---: | :---: | :---: | :---: | :---: |
| changable range of MTreg | binary | $\begin{gathered} 0001 \_1111 \\ (\text { sensitivity : default * } 0.45 \text { ) } \end{gathered}$ | $\begin{gathered} \text { 0100_0101 } \\ \text { default } \end{gathered}$ | $\begin{gathered} 1111 \text { _1110 } \\ \text { ( sensitivity : default * } 3.68 \text { ) } \end{gathered}$ |
|  | decimal | $\begin{gathered} 31 \\ (\text { sensitivity : default * } 0.45 \text { ) } \end{gathered}$ | $\begin{gathered} 69 \\ \text { default } \end{gathered}$ | $\begin{gathered} 254 \\ \text { ( sensitivity : default * } 3.68 \text { ) } \end{gathered}$ |

It is possilbe to detect 0.231 x by using this function at H -resolution mode. And it is possilbe to detect 0.11 lx by using this function at H -resolution mode2.

The below formula is to calculate illuminance per 1 count.
H-reslution mode: Illuminance per 1 count ( $\mathrm{Ix} /$ count ) $=1 / 1.2$ *( $69 / \mathrm{X}$ )
H-reslution mode2: Illuminance per 1 count (lx/count) $=1 / 1.2 *(69 / X) / 2$
1.2 : Measurement accuracy

69 : Default value of MTreg ( dec )
X : MTreg value
The below table is seeing the detail of resolution.

| MTreg value | Ix / count <br> at H-resolution mode | x / count <br> at H-resolution mode2 |
| :---: | :---: | :---: |
| $0001 \_1111$ | 1.85 | 0.93 |
| $0100 \_0101$ | 0.83 | 0.42 |
| $1111 \_1110$ | 0.23 | 0.11 |

## -H-Resolution Mode2

H-resolution mode2 is 0.5 lx (typ.) resolution mode. It is suitable if under less than 10 lx measurement data is necessary. This measurement mode supports "Adjust measurement result for influence of optical window ". Please refer it. It is possible to detect min. 0.11 lx by using H -resolution mode2.

Olnstruction set architecture for H -resolution mode2

| Instruction | Opecode | Comments |
| :--- | :---: | :--- |
| Continuously H-Resolution Mode2 | $0001 \_0001$ | Start measurement at 0.51x resolution. <br> Measurement Time is typically 120ms. |
| One Time H-Resolution Mode2 | $0010 \_0001$ | Start measurement at 0.5lx resolution. <br> Measurement Time is typically 120ms. <br> It is automatically set to Power Down mode after measurement. |

OMeasurement sequence example from "Write instruction" to "Read measurement result"
ex) Continuously H-resolution mode2 ( ADDR = 'L' )

(1) Send "Continuously H-resolution mode2" instruction

| ST | 0100011 | 0 | Ack | 00010001 | Ack | SP |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |

(2) Wait to complete 1st H -resolution mode2 measurement.( max. 180ms.)
(3) Read measurement result.

| ST | 0100011 | 1 | Ack | $\begin{gathered} \text { High Byte [15:8] } \\ 2^{14} \\ 2^{13} \end{gathered} 2^{12} \quad 2^{11} 2^{10} 82^{9} \quad 2^{8} \quad 2^{7}$ | Ack |
| :---: | :---: | :---: | :---: | :---: | :---: |



How to calculate when the data High Byte is " 00000000 " and Low Byte is "00010010"

$$
\left(2^{3}+2^{0}\right) / 1.2 \fallingdotseq 7.5[\mathrm{~lx}]
$$

## - Terminal Description



[^2]
## -Package Outlines



$0.145 \pm 0.05$

## WSOF6I ( Unit : mm )

PD area ( $0.25 \mathrm{~mm} \times 0.3 \mathrm{~mm}$ )

Please design the optical window so that light can cover at least this area.

## - The method of distinguishing 1pin.

There is some method of distinguishing 1 pin.
(1) Distinguishing by 1 Pin wide-lead
(2) Distinguishing by die pattern
(3) Distinguishing by taper part of 1-3pin side
(4) Distinguishing by 1 Pin line marking
(4) (by 1 Pin line marking ) is the easiest method to distinguish by naked eye.


## - Notes for use

1) Absolute Maximum Ratings

An excess in the absolute maximum ratings, such as supply voltage ( Vmax ), temperature range of operating conditions ( Topr ), etc., can break down devices, thus making impossible to identify breaking mode such as a short circuit or an open circuit. If any special mode exceeding the absolute maximum ratings is assumed, consideration should be given to take physical safety measures including the use of fuses, etc.
2) GND voltage

Make setting of the potential of the GND terminal so that it will be maintained at the minimum in any operating state. Furthermore, check to be sure no terminals are at a potential lower than the GND voltage including an actual electric transient.
3) Short circuit between terminals and erroneous mounting

In order to mount ICs on a set PCB, pay thorough attention to the direction and offset of the ICs. Erroneous mounting can break down the ICs. Furthermore, if a short circuit occurs due to foreign matters entering between terminals or between the terminal and the power supply or the GND terminal, the ICs can break down.
4) Operation in strong electromagnetic field

Be noted that using ICs in the strong electromagnetic field can malfunction them.
5) Inspection with set PCB

On the inspection with the set PCB, if a capacitor is connected to a low-impedance IC terminal, the IC can suffer stress. Therefore, be sure to discharge from the set PCB by each process. Furthermore, in order to mount or dismount the set PCB to/from the jig for the inspection process, be sure to turn OFF the power supply and then mount the set PCB to the jig. After the completion of the inspection, be sure to turn OFF the power supply and then dismount it from the jig. In addition, for protection against static electricity, establish a ground for the assembly process and pay thorough attention to the transportation and the storage of the set PCB.
6) Input terminals

In terms of the construction of IC, parasitic elements are inevitably formed in relation to potential. The operation of the parasitic element can cause interference with circuit operation, thus resulting in a malfunction and then breakdown of the input terminal. Therefore, pay thorough attention not to handle the input terminals; such as to apply to the input terminals a voltage lower than the GND respectively, so that any parasitic element will operate. Furthermore, do not apply a voltage to the input terminals when no power supply voltage is applied to the IC. In addition, even if the power supply voltage is applied, apply to the input terminals a voltage lower than the power supply voltage or within the guaranteed value of electrical characteristics.
7) Thermal design

Perform thermal design in which there are adequate margins by taking into account the power dissipation ( Pd ) in actual states of use.
8) Treatment of package

Dusts or scratch on the photo detector may affect the optical characteristics. Please handle it with care.
9) Rush current

When power is first supplied to the CMOS IC, it is possible that the internal logic may be unstable and rush current may flow instantaneously. Therefore, give special consideration to power coupling capacitance, power wiring, width of GND wiring, and routing of connections.
10)The exposed central pad on the back side of the package

There is an exposed central pad on the back side of the package. Please mount by Footprint dimensions described in the Jisso Information for WSOF6I. This pad is GND level, therefore there is a possibility that LSI malfunctions and heavy-current is generated.

## - Ordering part number



Part No.


Part No.


Package FVI: WSOF6I


Packaging and forming specification TR: Embossed tape and reel

## WSOF6I



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[^0]:    ※1 White LED is used as optical source.
    $※ 2$ Measurement Accuracy typical value is possible to change ' 1 ' by "Measurement result adjustment function".
    ※3 Use H-resolution mode or H-resolution mode2 if dark data (less than 10 lx ) is need.

[^1]:    *"active state" is that BH 1751 FVI works and accept $\mathrm{I}^{2} \mathrm{C}$ bus access correctly.

[^2]:    ※These values are design-value, not guaranteed.

